



Feature

- 2.5V to 5.5V Input Voltage Range
- Two Buck Converters
- Output Voltage Range: 0.6V to Vin
- Maximum Continuous Load Current:1.5A (2CH total output power consumption must be less than 5W)
- Fixed 1.5MHz Switching Frequency
- 100% Duty Cycle Low Dropout Operation

Applications

- Wi-Fi Card
- Wi-Fi Router/AP

General Description

The RY1302 is a 2-CH power management IC for applications powered by one Li-Ion battery or a DC 5V adapter. It integrates dual synchronous buck regulators and can provide high efficiency output at light load and heavy load operation. The internal compensation architecture simplifies the application circuit design. Besides, the independent enable control makes the designer have the greatest flexibility to optimize timing for power sequencing purposes. The RY1302 is available in a 10 pin DFN package.

Typical Application Circuit

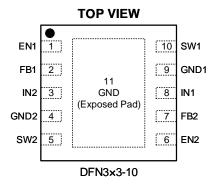
V_{IN}5V VIN1 С 10µF L₁ 2.2µH V_{OUT1} 1.2V lsw[,] VIN2 C_4 C_2 51K (opt.) 10µF C-FB1 22µF R₂ VOUT2 1.5V L₁2.2µH ∃sw₂ R₂ C₅ (opt.) EN1 ON/OFF 76.5ł FB2 EN2 ON/OFF

- <1µA Shutdown Current
- Independent Enable Control
- Internal Compensation
- Cycle-by-Cycle Current Limit
- Short Circuit Protection
- Each Channel Efficiency Up to 95%
- Auto Recovery OTP Protection
- Available in 10-pin 3mm × 3mm DFN Package
- GPS
- STB



PIN Description

Pin Configuration



Top Marking: 1302 <u>YYLL</u> (device code: 1302, YY=year code, LL= lot number code)

Pin Description

Item	Name	Function Description
1	EN1	CH1 turns on/turns off control input. Drive EN above 1.5V to turn on the part. Drive
1		EN below 0.6V to turn it off. In shutdown, don't leave this pin floating.
2 FB1	ED1	Feedback input of CH1. Connect FB to the center point of the external resistor divider.
	ГЫ	The feedback threshold voltage is 0.6V.
2 1	IN2	Power input pin of CH1. Recommended to use a 10uF MLCC capacitor
3	11N2	between IN2 pin and GND2 pin.
4	GND2	Ground pin of CH2.
5	GW/2	Internal MOSFET switching output of CH2. Connect SW2 pin with a low
5	SW2	pass filter circuit to obtain a stable DC output voltage.
6	END	CH1 turns on/turns off control input. Drive EN above 1.5V to turn on the part. Drive
0	EN2	EN below 0.6V to turn it off. In shutdown. Don't leave this pin floating.
7	FB2	Feedback input of CH2. Connect FB to the center point of the external resistor divider.
1	ΓΒΖ	The feedback threshold voltage is 0.6V.
8	IN1	Power input pin of CH1. Recommended to use a 10uF MLCC capacitor
0		between IN1 pin and GND1 pin.
9	GND1	Ground pin of CH1.
10	SW1	Internal MOSFET switching output of CH1. Connect SW1 pin with a low
10		pass filter circuit to obtain a stable DC output voltage.
11	Exposed Pad	The Exposed Pad must be soldered to the ground plane on the PCB.

Order Information ⁽¹⁾

Marking	Part No.	Model	Description	Package	T/R Qty
1302 <u>YYLL</u>	70302001	RY1302	RY1302 2×Buck, 2.5-5.5V, 1.5A, 1.5MHz, VFB 0.6V, DFN10-3×3	DFN10-3×3	3000

Note (1): All RYCHIP parts are Pb-Free and adhere to the RoHS directive.



Specifications

Absolute Maximum Ratings (1) (2)

Item	Min	Max	Unit
V _{IN1} , V _{IN2} Voltage	-0.3	6.5	V
V _{SW1} , V _{SW2} Voltage	-0.3	V _{IN} +0.3V	V
All Other Pins Voltage	-0.3 6.5		V
Power Dissipation ⁽³⁾	Internally Lim	Internally Limited	
Operating Junction Temperature, T _J	-40	150	°C
Storage Temperature, T _{stg}	-55	150	°C
Lead Temperature (Soldering, 10sec.)		260	°C

Note (1): Exceeding these ratings may damage the device.

Note (2): The device is not guaranteed to function outside of its operating conditions.

Note (3): The maximum allowable power dissipation is a function of the maximum junction temperature, $T_{J(MAX)}$, the junction-to-ambient thermal resistance, $R_{\theta JA}$, and the ambient temperature, T_A . The maximum allowable power dissipation at any ambient temperature is calculated using: $P_{D(MAX)} = (T_{J(MAX)} - T_A)/R_{\theta JA}$. Exceeding the maximum allowable power dissipation causes excessive die temperature, and the regulator goes into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage. Thermal shutdown engages at $T_J=160^{\circ}C$ (typical) and disengages at $T_J=130^{\circ}C$ (typical).

ESD Ratings

Item	Description	Value	Unit
	Human Body Model (HBM)		
V _(ESD-HBM)	ANSI/ESDA/JEDEC JS-001-2014	± 2000	V
	Classification, Class: 2		
	Charged Device Mode (CDM)		
V _(ESD-CDM)	ANSI/ESDA/JEDEC JS-002-2014	±200	V
	Classification, Class: C0b		
	JEDEC STANDARD NO.78E APRIL 2016		
ILATCH-UP	Temperature Classification,	±150	mA
	Class: I		

Recommended Operating Conditions

Item	Min	Max	Unit
Operating Junction Temperature ⁽¹⁾	-40	125	°C
Operating Temperature Range	-40	85	°C
Each Channel Input Voltage	2.7	5.5	V
Each Channel Output Current	0	1.5	А

Note (1): All limits specified at room temperature ($TA = 25^{\circ}C$) unless otherwise specified. All room temperature limits are 100% production tested. All limits at temperature extremes are ensured through correlation using standard Statistical Quality Control (SQC) methods. All limits are used to calculate Average Outgoing Quality Level (AOQL).



Thermal Information

Item	Description	Value	Unit
$R_{\theta JA}$	Junction-to-ambient thermal resistance ⁽¹⁾⁽²⁾	40.6	°C/W
R _{0JC(top)}	Junction-to-case (top) thermal resistance	45.5	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	15.9	°C/W
ΨJT	Junction-to-top characterization parameter	0.4	°C/W
Ψ _{JB}	Junction-to-board characterization parameter	15.7	°C/W
$R_{\theta JC}$	Junction-to-case (Bottom) thermal resistance	2.8	°C/W

Note (1): The package thermal impedance is calculated in accordance to JESD 51-7.

Note (2): Thermal Resistances were simulated on a 4-layer, JEDEC board

Electrical Characteristics (1) (2)

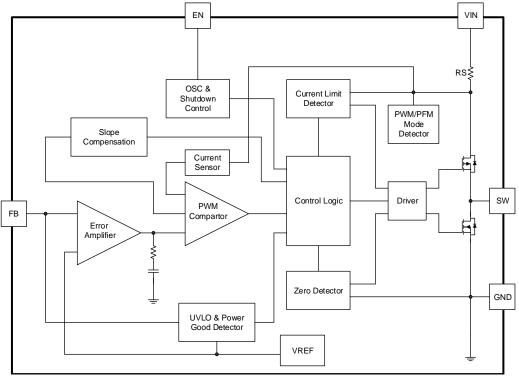
Parameter	Conditions	Min.	Тур.	Max.	Unit
Input Voltage Range		2.7		5.5	V
Supply Current (Quiescent)	$V_{EN} = 3.0 V$		80		μΑ
Supply Current (Shutdown)	$V_{EN} = 0$ or $EN = GND$		0.1	1.0	μΑ
Feedback Voltage		0.585	0.600	0.615	V
High-Side Switch On-Resistance	I _{SW} =100mA		80		mΩ
Low-Side Switch On-Resistance	I _{SW} =-100mA		50		mΩ
Upper Switch Current Limit		2.5			А
Over Voltage Protection Threshold			6.2		V
Switching Frequency			1.5		MHz
Maximum Duty Cycle			100		%
EN Rising Threshold		1.2			V
EN Falling Threshold				0.6	V
	Wake up V_{IN} Voltage		2.5	2.6	V
Under-Voltage Lockout Threshold	Shutdown V _{IN} Voltage	1.8	1.9		V
	Hysteresis V _{IN} voltage		600		mV
Soft Start			0.8		mS
Thermal Shutdown			160		°C
Thermal Hysteresis			30		°C

Note (1): MOSFET on-resistance specifications are guaranteed by correlation to wafer level measurements.

Note (2): Thermal shutdown specifications are guaranteed by correlation to the design and characteristics analysis.



Single Channel Functional Block Diagram



Block Diagram

Functions Description

Feature Description

RY1302 is a highly efficient and integrated Power Management IC for Systems-on-a-Chip (SoCs), ASICs, and processors. The device incorporates 3 high-efficiency synchronous buck regulators.

Each of the buck regulators is specially designed for high-efficiency operation throughout the load range. With 1.2MHz typical switching frequency, the external LC filter can be small and still provide very low output voltage ripple. The bucks are internally compensated to be stable with the recommended external inductors and capacitors as detailed in the application diagram. Synchronous rectification yields high efficiency for low voltage and high output currents.

Additional features include soft-start, under-voltage lockout, bypass, and current and thermal overload protection. 3 channel BUCKs are nearly identical in performance and mode of operation. They can operate in automatic mode (PFM/PWM). At very light loads, BUCKs enter PFM mode and operate with reduced switching frequency and supply current to maintain high efficiency.

Internal Regulator

The RY1302 is a 3-channel current mode step down DC/DC converter that provides excellent transient response with no extra external compensation components. This device contains an internal, low resistance, high voltage power MOSFET, and operates at a high 1.2MHz operating frequency to ensure a compact, high efficiency design with excellent performance.



Current Limit

A current limit feature protects the device and any external components during overload conditions. In PWM mode the current limiting is implemented by using an internal comparator that trips at current levels according to the buck capability. If the output is shorted to ground the device enters a timed current limit mode where the NFET is turned on for a longer duration until the inductor current falls below a low threshold, ensuring inductor current has more time to decay, thereby preventing runaway.

Under-Voltage Lockout (UVLO)

Under-voltage lockout (UVLO) protects the chip from operating at an insufficient supply voltage. UVLO protection monitors the internal regulator voltage. When the voltage is lower than UVLO threshold voltage, the device is shut off. When the voltage is higher than UVLO threshold voltage, the device is enabled again.

Thermal Shutdown

Thermal shutdown prevents the chip from operating at exceedingly high temperatures. When the silicon die temperature exceeds 160°C, it shuts down the whole chip. When the temperature falls below its lower threshold (Typ. 130°C) the chip is enabled again.

Internal Soft-Start

The soft-start is implemented to prevent the converter output voltage from overshooting during startup. When the chip starts, the internal circuitry generates a soft-start voltage (SS) ramping up from 0V to 0.6V. When it is lower than the internal reference (REF), SS overrides REF so the error amplifier uses SS as the reference. When SS is higher than REF, REF regains control. The SS time is internally to 1ms.

Applications Information

Setting the Output Voltage

Each channel requires an input capacitor, an output capacitor, and an inductor. These components are critical to the performance of the device. RY1302 are internally compensated and do not require external components to achieve stable operation. The output voltage can be programmed by resistor divider.

$$V_{OUT} = V_{FB} \times \frac{R1 + R2}{R2}$$

When sizing R2, in order to achieve low current consumption and acceptable noise sensitivity, use a maximum of $100k\Omega$ for R2. Larger currents through R2 improve noise sensitivity and output voltage accuracy but increase current consumption.

Selecting the Inductor

The recommended inductor values are shown in the Application Diagram. It is important to guarantee the inductor core does not saturate during any foreseeable operational situation. The inductor should be rated to handle the maximum inductor peak current: Care should be taken when reviewing the different saturation current ratings that are specified by different manufacturers. Saturation current ratings are typically specified at 25°C, so ratings at maximum ambient temperature of the application should be requested from the manufacturer. The inductor value



can be calculated with:

$$L = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times \Delta I_L \times F_{OSC}}$$

Where ΔI_L is the inductor ripple current. Choose inductor ripple current to be approximately 30% to 40% of the maximum load current. The maximum inductor peak current can be estimated as:

$$I_{L(MAX)} = I_{LOAD} + \frac{\Delta I_L}{2}$$

Under light load conditions below 100mA, larger inductance is recommended for improved efficiency. Larger inductances lead to smaller ripple currents and voltages, but they also have larger physical dimensions, lower saturation currents and higher linear impedance. Therefore, the choice of inductance should be compromised according to the specific application.

Selecting the Input Capacitor

The input current to the step-down converter is discontinuous and therefore requires a capacitor to supply AC current to the step-down converter while maintaining the DC input voltage. For a better performance, use ceramic capacitors placed as close to VIN as possible and a 0.1μ F input capacitor to filter out high frequency interference is recommended. Capacitors with X5R and X7R ceramic dielectrics are recommended because they are stable with temperature fluctuations.

The capacitors must also have a ripple current rating greater than the maximum input ripple current of the converter. The input ripple current can be estimated with Equation:

$$I_{CIN} = I_{OUT} \times \sqrt{\frac{V_{OUT}}{V_{IN}}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

From the above equation, it can be concluded that the input ripple current reaches its maximum at $V_{IN}=2V_{OUT}$ where $I_{CIN} = \frac{I_{OUT}}{2}$. For simplification, choose an input capacitor with an RMS current rating greater than half of the maximum load current.

The input capacitance value determines the input voltage ripple of the converter. If there is an input voltage ripple requirement in the system, choose the input capacitor that meets the specification. The input voltage ripple can be estimate with Equation:

$$\Delta V_{IN} = \frac{I_{OUT}}{F_{OSC} \times C_{IN}} \times \frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

Similarly, when $V_{IN}=2V_{OUT}$, input voltage ripple reaches its maximum of $\Delta V_{IN} = \frac{1}{4} \times \frac{I_{OUT}}{F_{OSC} \times C_{IN}}$.

Selecting the Output Capacitor

An output capacitor is required to maintain the DC output voltage. The output voltage ripple can be estimated with Equation:

$$\Delta V_{OUT} = \frac{V_{OUT}}{F_{OSC} \times L} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \times \left(R_{ESR} + \frac{1}{8 \times F_{OSC} \times C_{OUT}}\right)$$

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There are some differences between different types of capacitors. In the case of ceramic capacitors, the impedance at the switching frequency is dominated by the capacitance. The output voltage ripple is mainly caused by the capacitance. For simplification, the output voltage ripple can be estimated with Equation:

$$\Delta V_{OUT} = \frac{V_{OUT}}{8 \times F_{OSC}^2 \times L \times C_{OUT}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

A larger output capacitor can achieve a better load transient response, but the maximum output capacitor limitation should also be considered in the design application. If the output capacitor value is too high, the output voltage will not be able to reach the design value during the soft-start time and will fail to regulate. The maximum output capacitor value (C_{OUT_MAX}) can be limited approximately with Equation:

$$C_{OUT_MAX} = \left(I_{LIM_AVG} - I_{OUT}\right) \times T_{SS}/V_{OUT}$$

Where L_{LIM AVG} is the average start-up current during the soft-start period, and T_{SS} is the soft- start time.

On the other hand, special attention should be paid when selecting these components. The DC bias of these capacitors can result in a capacitance value that falls below the minimum value given in the recommended capacitor specifications table.

The ceramic capacitor's actual capacitance can vary with temperature. The capacitor type X7R, which operates over a temperature range of -55° C to $+125^{\circ}$ C, will only vary the capacitance to within $\pm 15^{\circ}$. The capacitor type X5R has a similar tolerance over a reduced temperature range of -55° C to $+85^{\circ}$ C. Many large value ceramic capacitors, larger than 1uF are manufactured with Z5U or Y5V temperature characteristics. Their capacitance can drop by more than 50% as the temperature varies from 25°C to 85°C. Therefore, X5R or X7R is recommended over Z5U and Y5V in applications where the ambient temperature will change significantly above or below 25°C.

Feed-Forward Capacitor (C_{FF})

RY1302 has internal loop compensation, so adding C_{FF} is optional. Specifically, for specific applications, if necessary, consider whether to add feed-forward capacitors according to the situation.

The use of a feed-forward capacitor (C_{FF}) in the feedback network is to improve the transient response or higher phase margin. For optimizing the feed-forward capacitor, knowing the cross frequency is the first thing. The cross frequency (or the converter bandwidth) can be determined by using a network analyzer. When getting the cross frequency with no feed-forward capacitor identified, the value of feed-forward capacitor (C_{FF}) can be calculated with the following Equation:

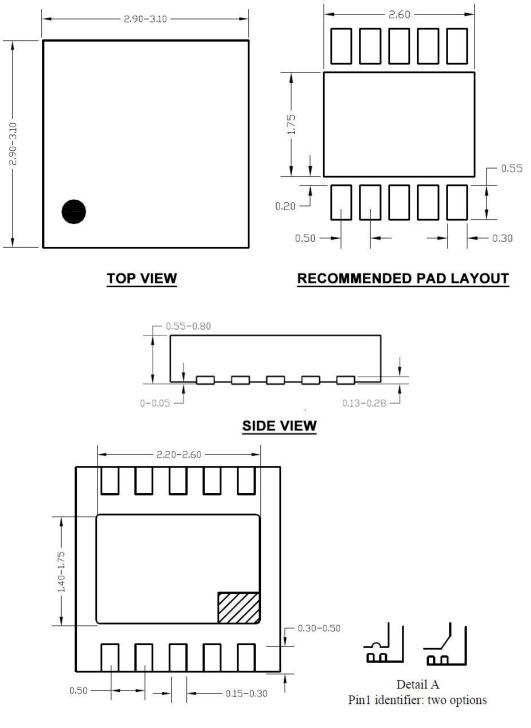
$$C_{FF} = \frac{1}{2\pi \times F_{CROSS}} \times \sqrt{\frac{1}{R1} \times \left(\frac{1}{R1} + \frac{1}{R2}\right)}$$

Where F_{CROSS} is the cross frequency.

To reduce transient ripple, the feed-forward capacitor value can be increased to push the cross frequency to higher region. Although this can improve transient response, it also decreases phase margin and cause more ringing. In the other hand, if more phase margin is desired, the feed-forward capacitor value can be decreased to push the cross frequency to lower region.



Package Description



BOTTOM VIEW

NOTE:

1. CONTROL DIMENSION IS IN INCHES. DIMENSION IN BRACKET IS IN MILLIMETERS.

- 2. PACKAGE LENGTH DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS.
- 3. PACKAGE WIDTH DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSIONS.
- 4. LEAD COPLANARITY (BOTTOM OF LEADS AFTER FORMING) SHALL BE 0.004" INCHES MAX.
- 5. DRAWING CONFORMS TO JEDEC MS-012, VARIATION BA.
- 6. DRAWING IS NOT TO SCALE.